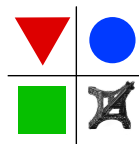


A multilayer model for non-hydrostatic multiscale free-surface flows

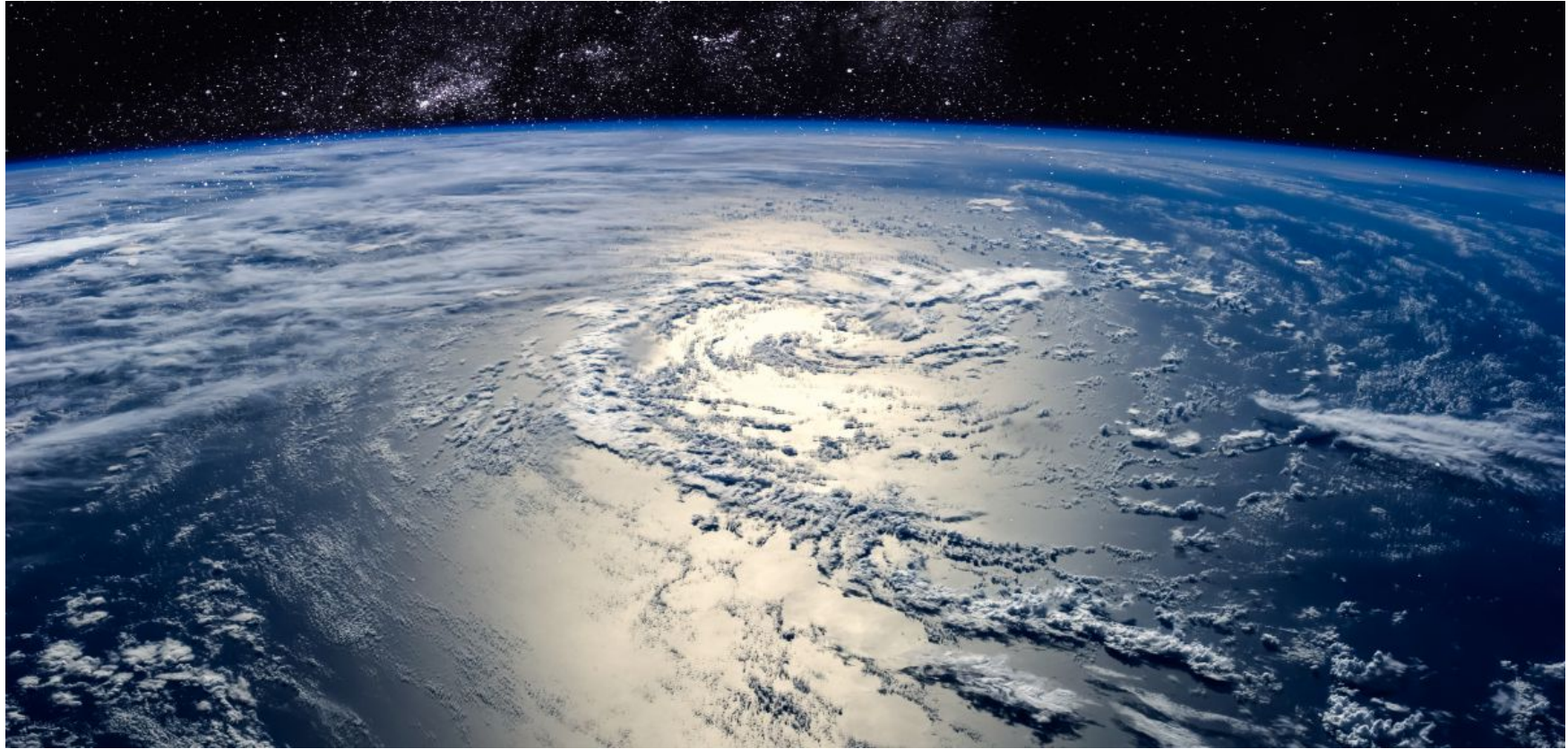
Stéphane Popinet

Institut ∂ 'Alembert

CNRS / Sorbonne Université



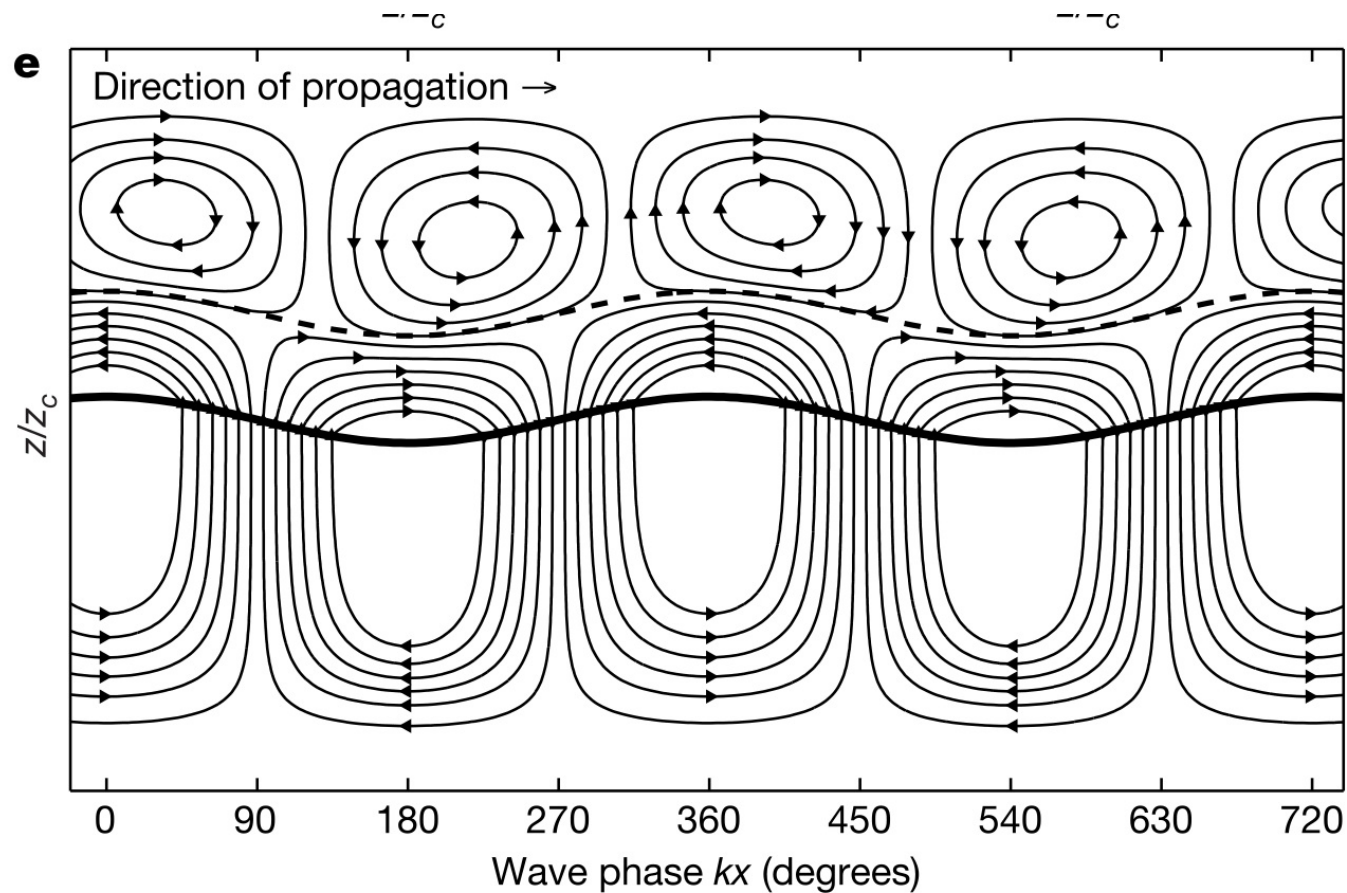
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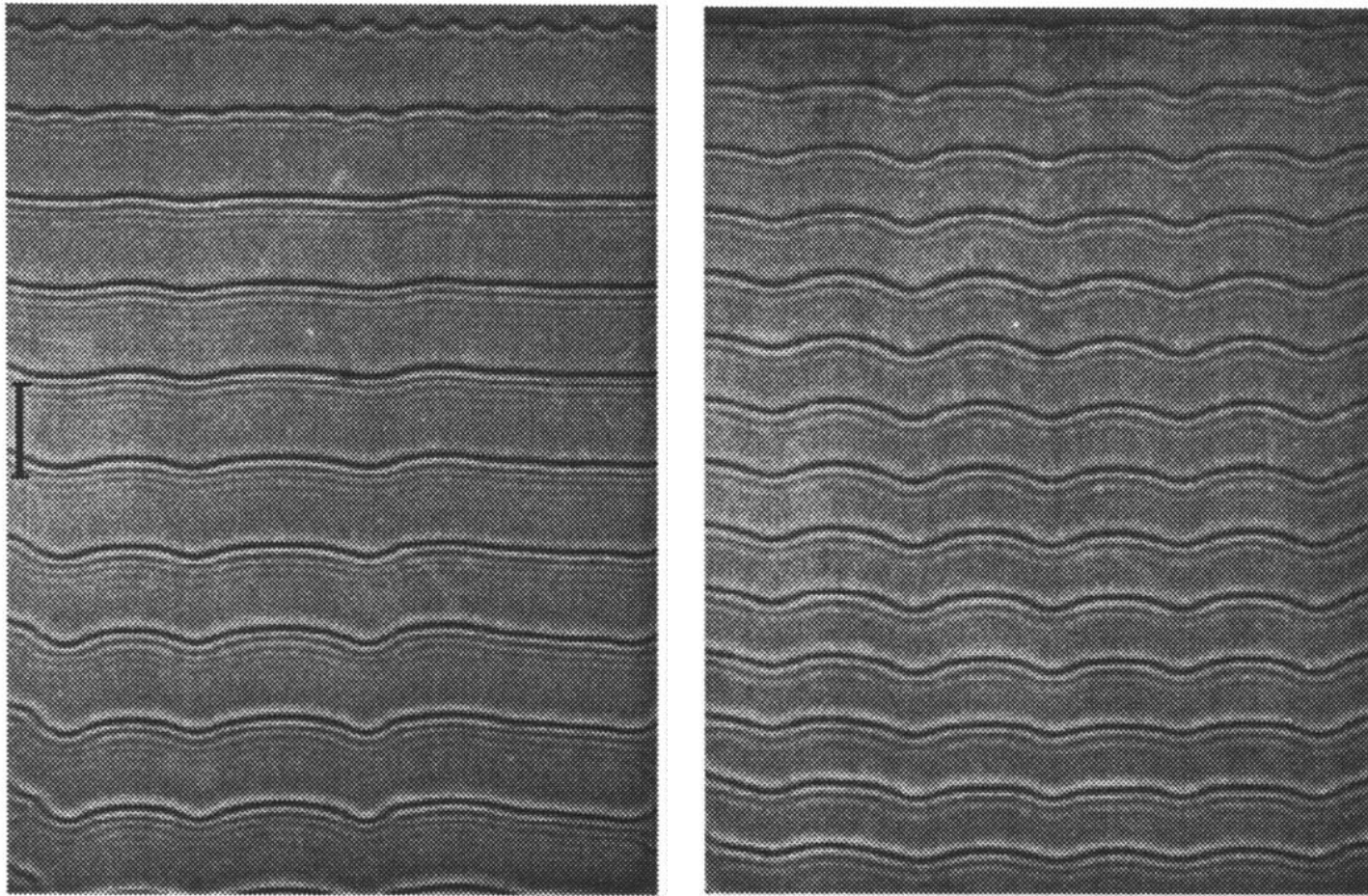


Sand Dunes, Mui Né, Vietnam





Hristov et al, *Dynamical coupling of wind and ocean waves through wave-induced air flow*, Nature, 2003.



Piotr Leonidovich Kapitza, "Wave flow of thin layers of a viscous fluid," in *Collected papers of P.L. Kapitza*, D. Ter Haar, Ed., pp. 662–689. Pergamon, 1948.

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Adhémar Jean-Claude Barré de Saint-Venant, 1871.

- + Simple
 - + System of conservation laws
 - + Fully non-linear
 - + Numerically efficient
 - Vertical structure is entirely modelled
 - Hydrostatic, no-vertical acceleration/momentum
- Non-dispersive waves: $c = \sqrt{g h}$



1797–1886

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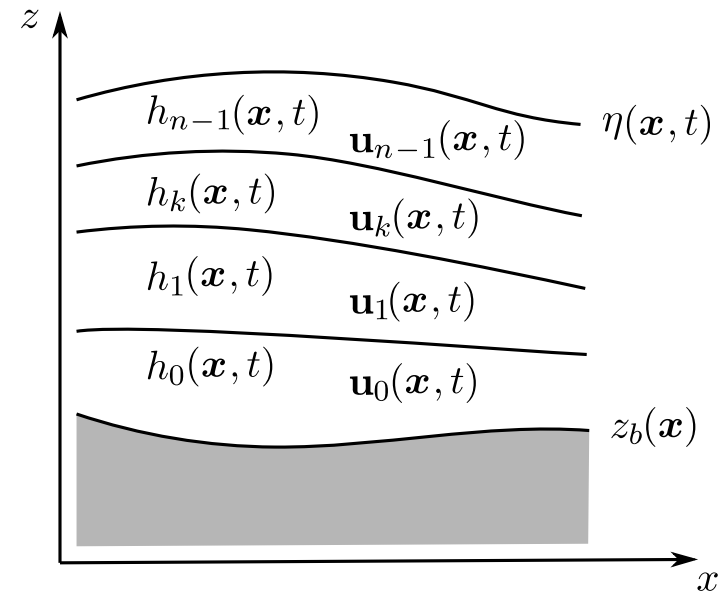


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The basis for the “primitive equations” of oceanic and atmospheric circulation models.

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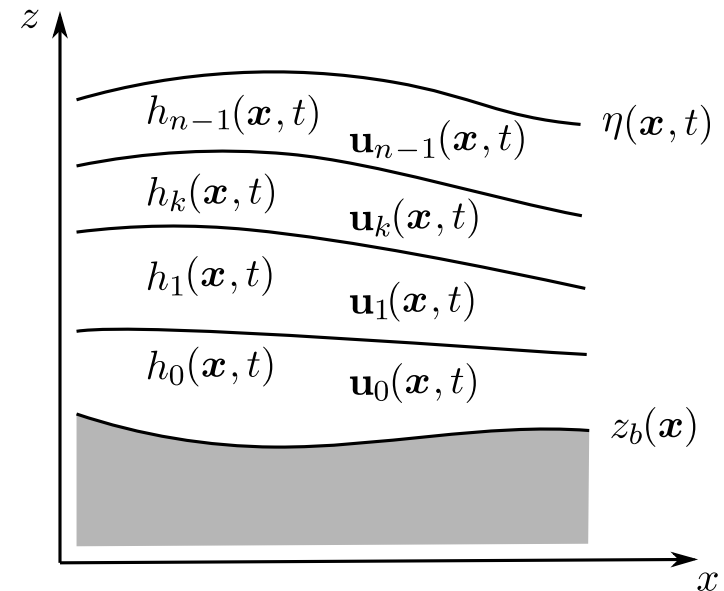


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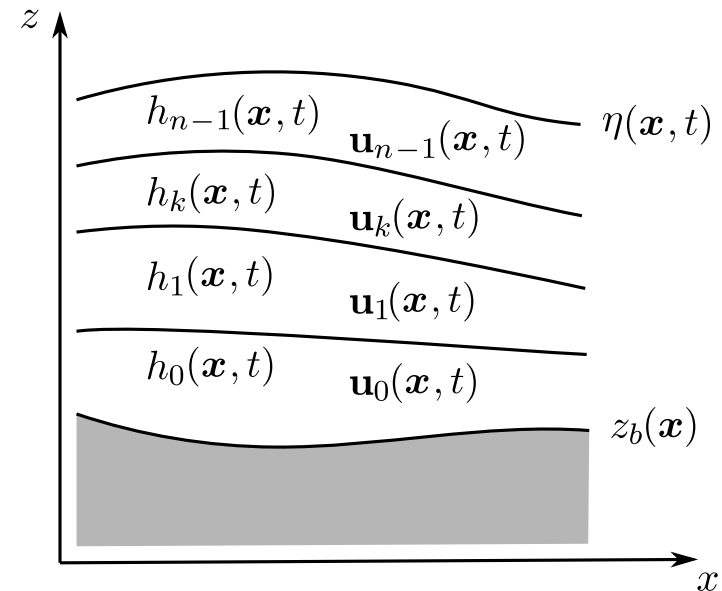


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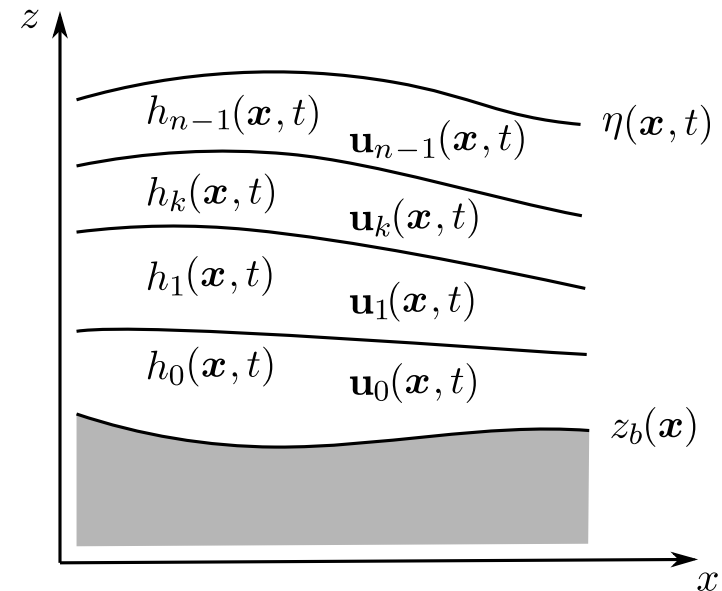


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Many more recent variants: Serre 1953, Peregrine 1968, Green-Naghdi 1976...

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- Complex asymptotic terms
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1842–1929

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M. BOUSSINESQ.

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$$\nabla \cdot \mathbf{u} = 0$$

$$\partial_t \chi(\mathbf{x}, t) = \mathbf{u}(\chi(\mathbf{x}, t), t)$$

Leonhard Euler, 1757 (without the free surface).

- + Complete/consistent system
- Complex boundary condition
- Link with Saint-Venant?
- How to represent χ ? (VOF, Levelset, Lagrangian etc.)
- Computational cost



1707-1783

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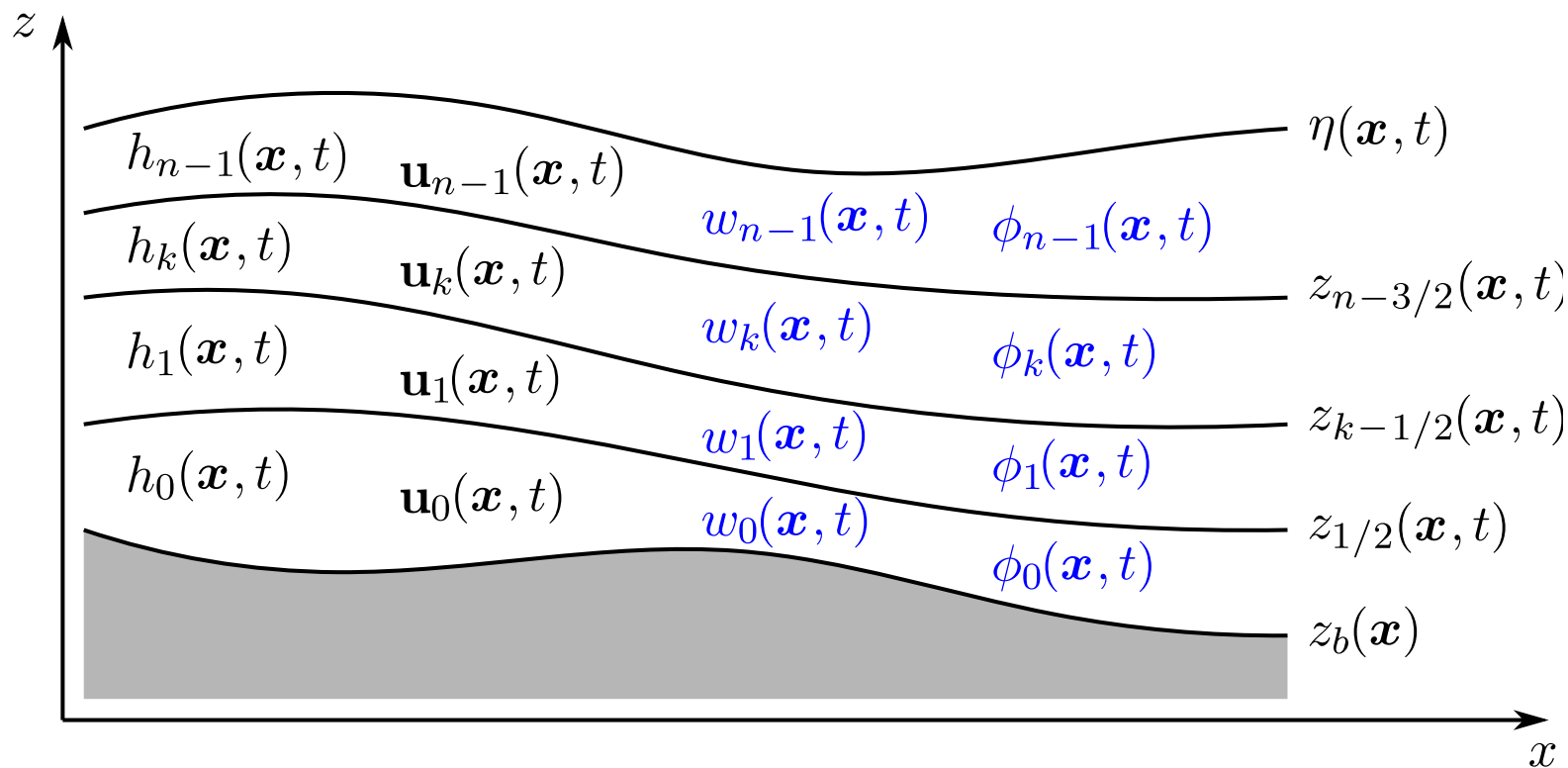
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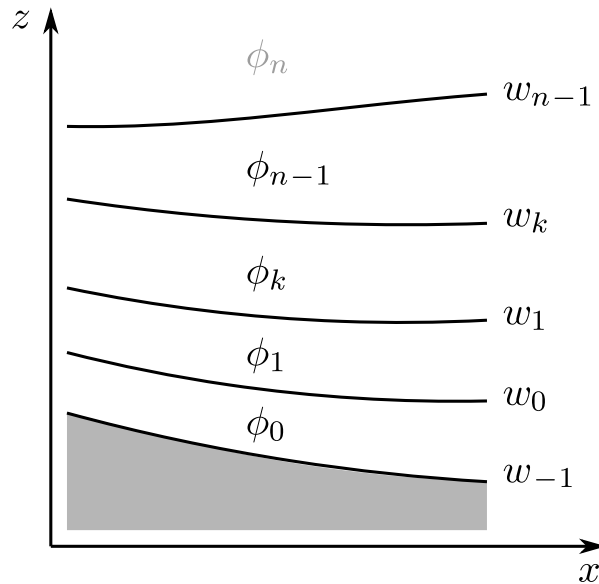
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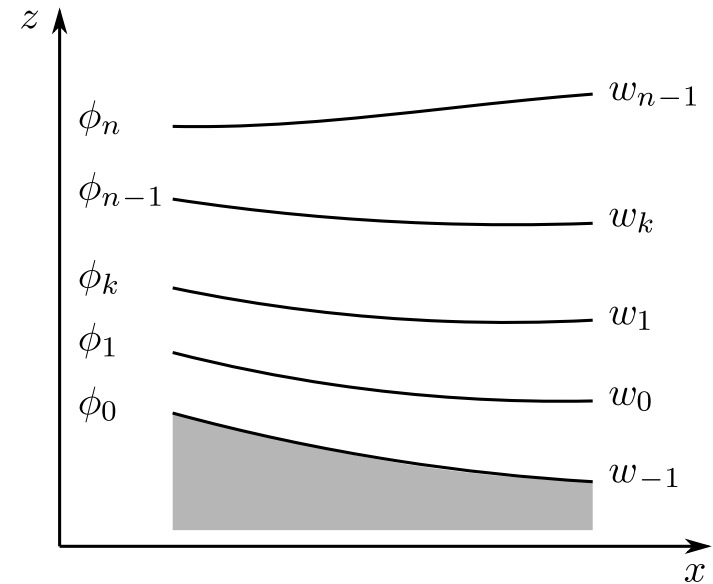
Examples of possible vertical discretisations



1917–2008



Lorenz grid



Keller grid (box scheme)

Edward Norton Lorenz, *Energy and numerical weather prediction*, 1960.

H. B. Keller, *A new difference scheme for parabolic problems*. 1971.

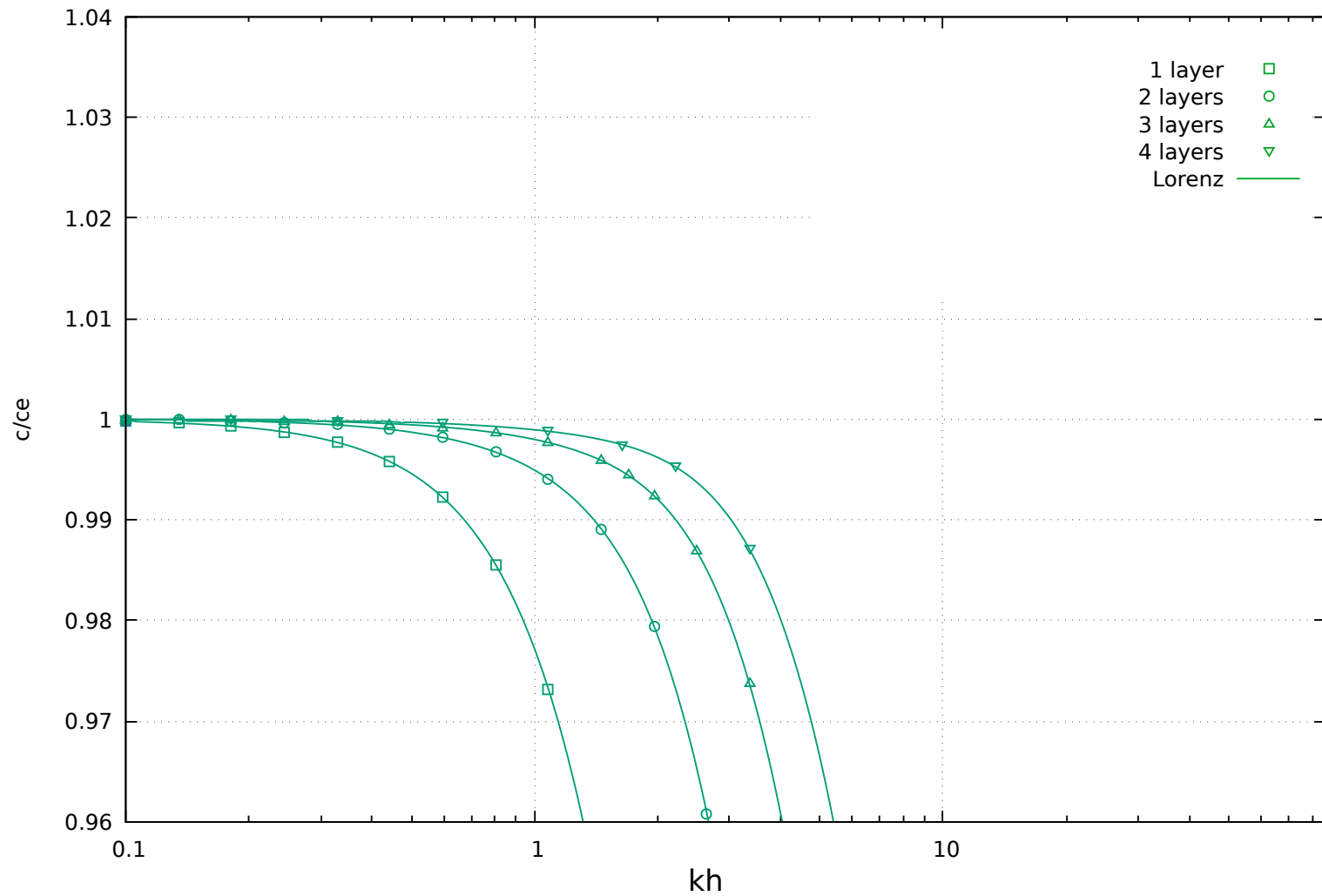
Zijlema & Stelling, *IJNMF*, 2005.

Which one is best? $\rightarrow$ choose the best dispersion relation based on the *linearised perturbation system* ($h_k = \bar{h}_k + h'_k e^{i(\hat{k}x - \omega t)}$, $u_k = u'_k e^{i(\hat{k}x - \omega t)}$, etc.)

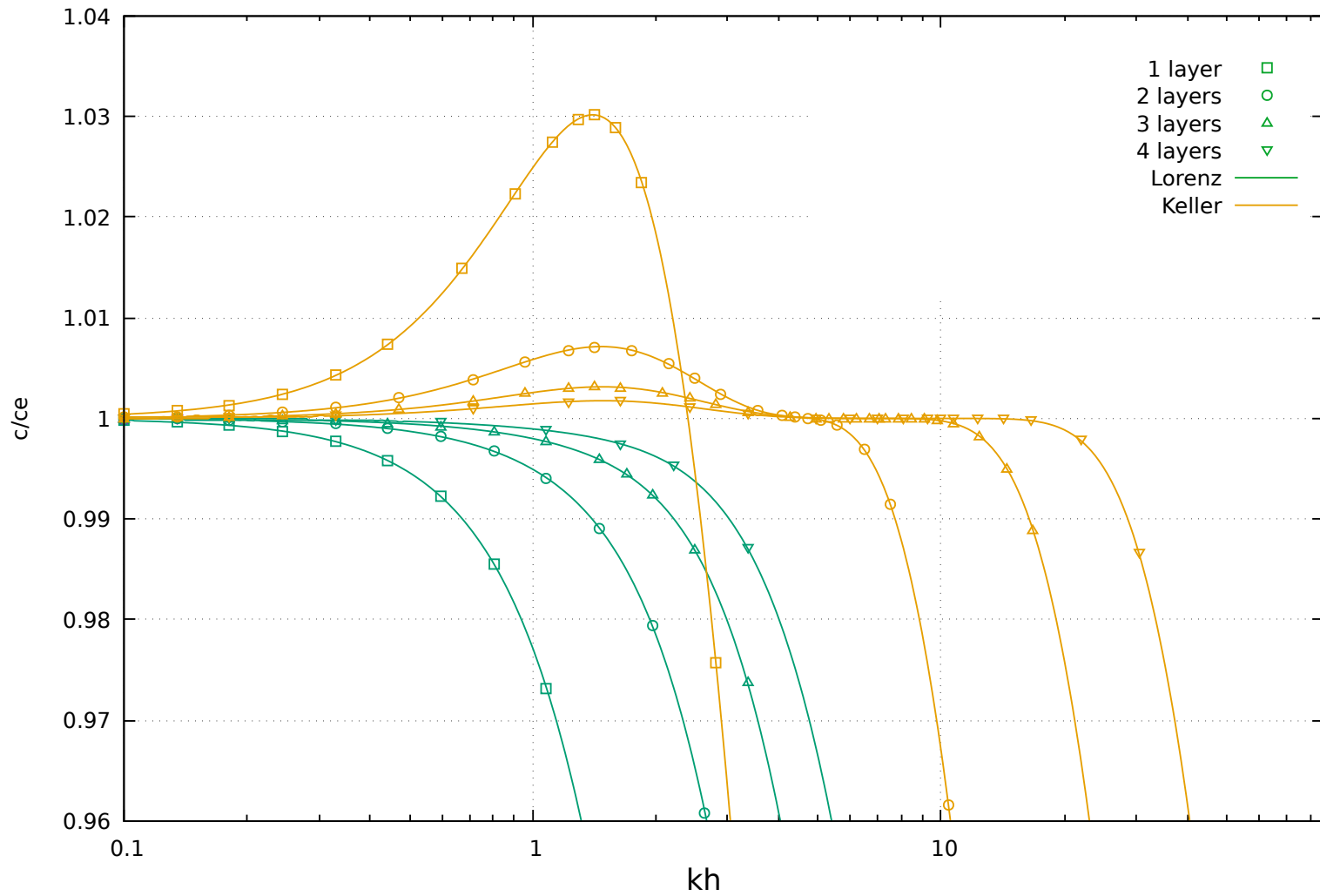
$$\begin{aligned} -\omega h'_k + \bar{h}_k u'_k \hat{k} &= 0, \\ -\bar{h}_k u'_k \omega &= -g \hat{k} \bar{h}_k \sum h'_k - \bar{h}_k \hat{k} \frac{\phi'_{k+1} + \phi'_k}{2}, \\ -\bar{h}_k \frac{w'_k + w'_{k-1}}{2} \omega i &= \phi'_k - \phi'_{k+1}, \\ \bar{h}_k u'_k \hat{k} i + w'_k - w'_{k-1} &= 0, \end{aligned}$$

Computing the determinant then gives (for two layers)

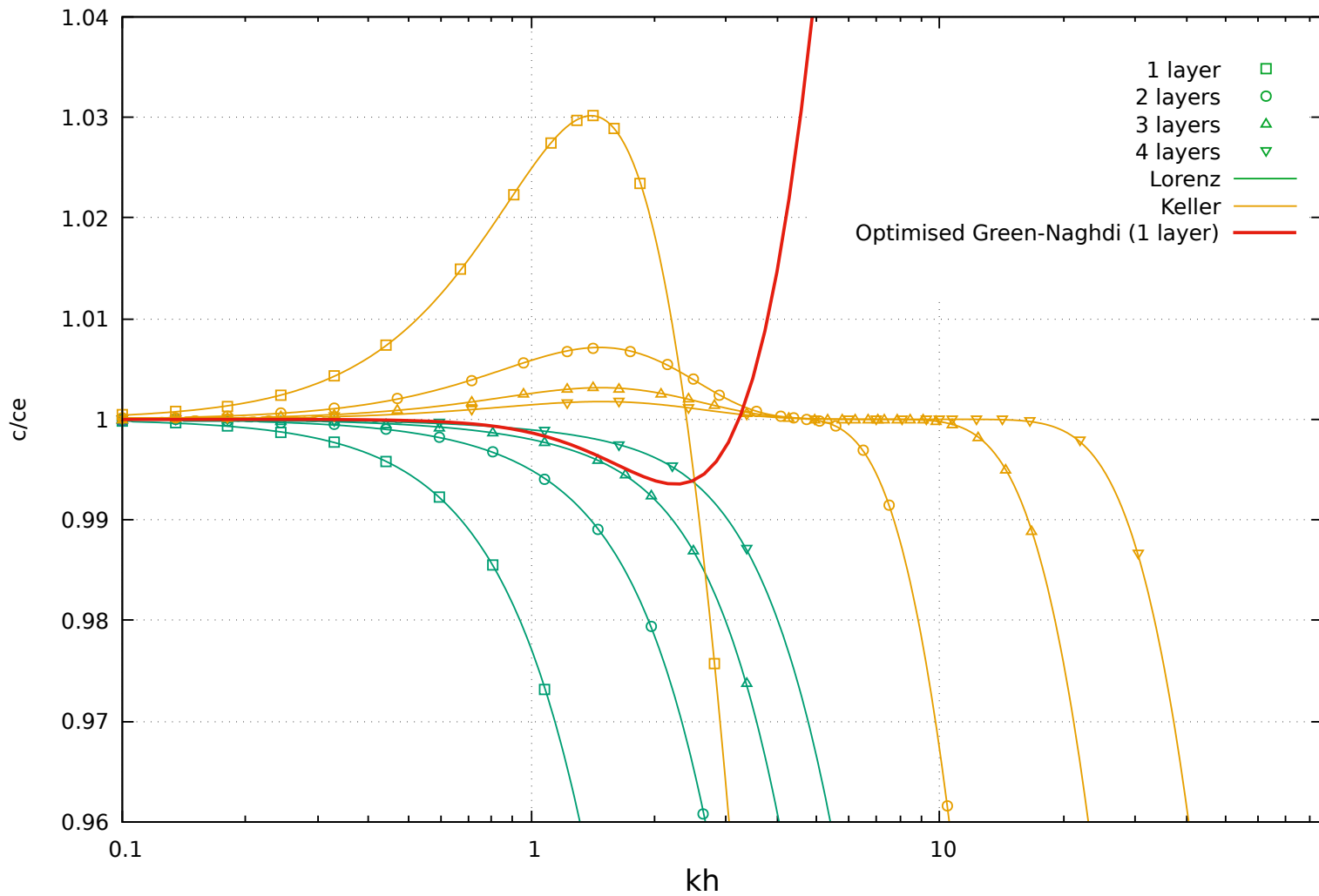
$$\omega_2^2(\hat{k}) = 8g \frac{h_0 h_1^2 \hat{k}^4 + (h_1 + h_0) \hat{k}^2}{3 h_0^2 h_1^2 \hat{k}^4 + 3 (3 h_0^2 + h_0 h_1 + h_1^2) \hat{k}^2 + 8}$$



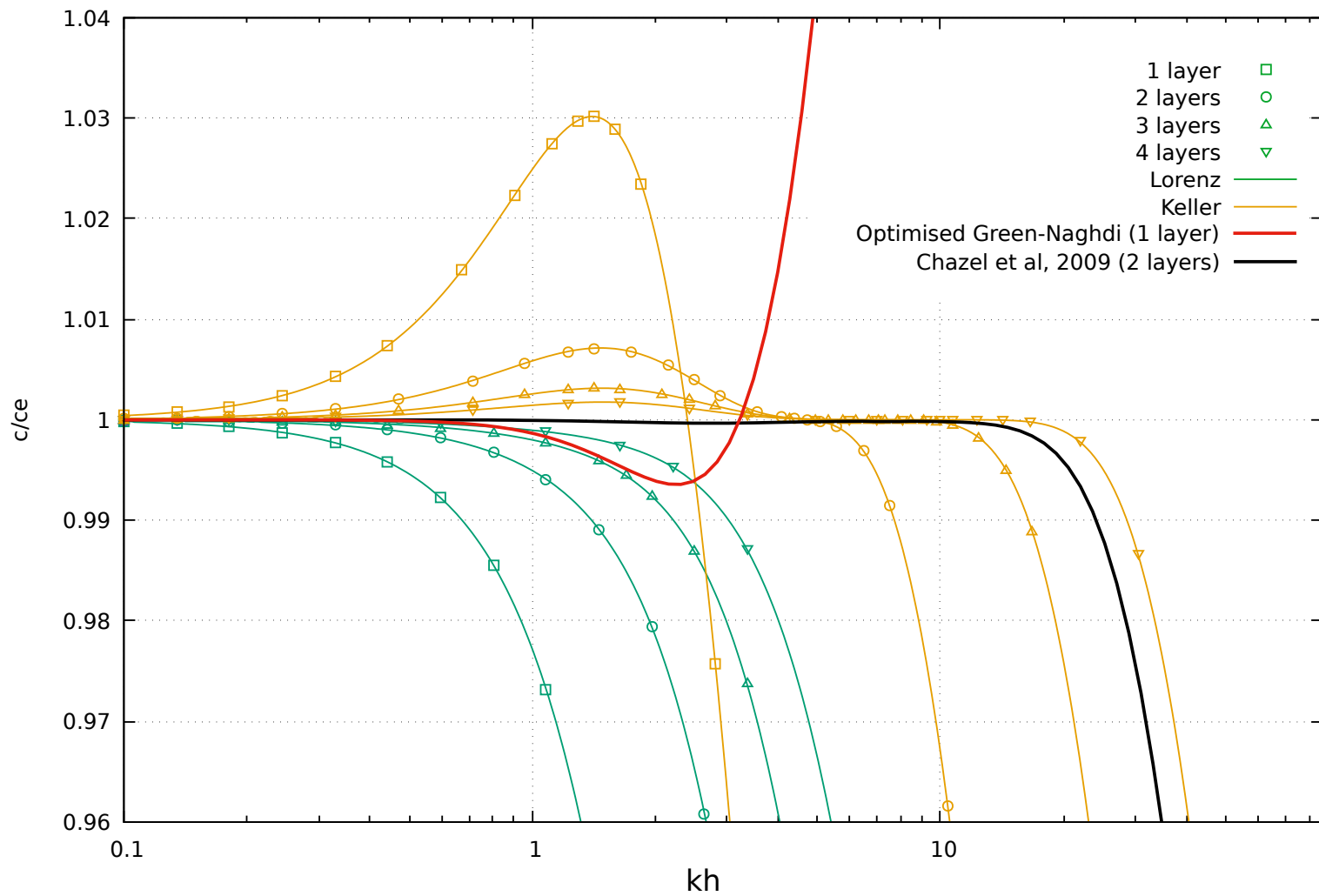
$$c_e^2 = \frac{g}{k} \tanh(kh)$$



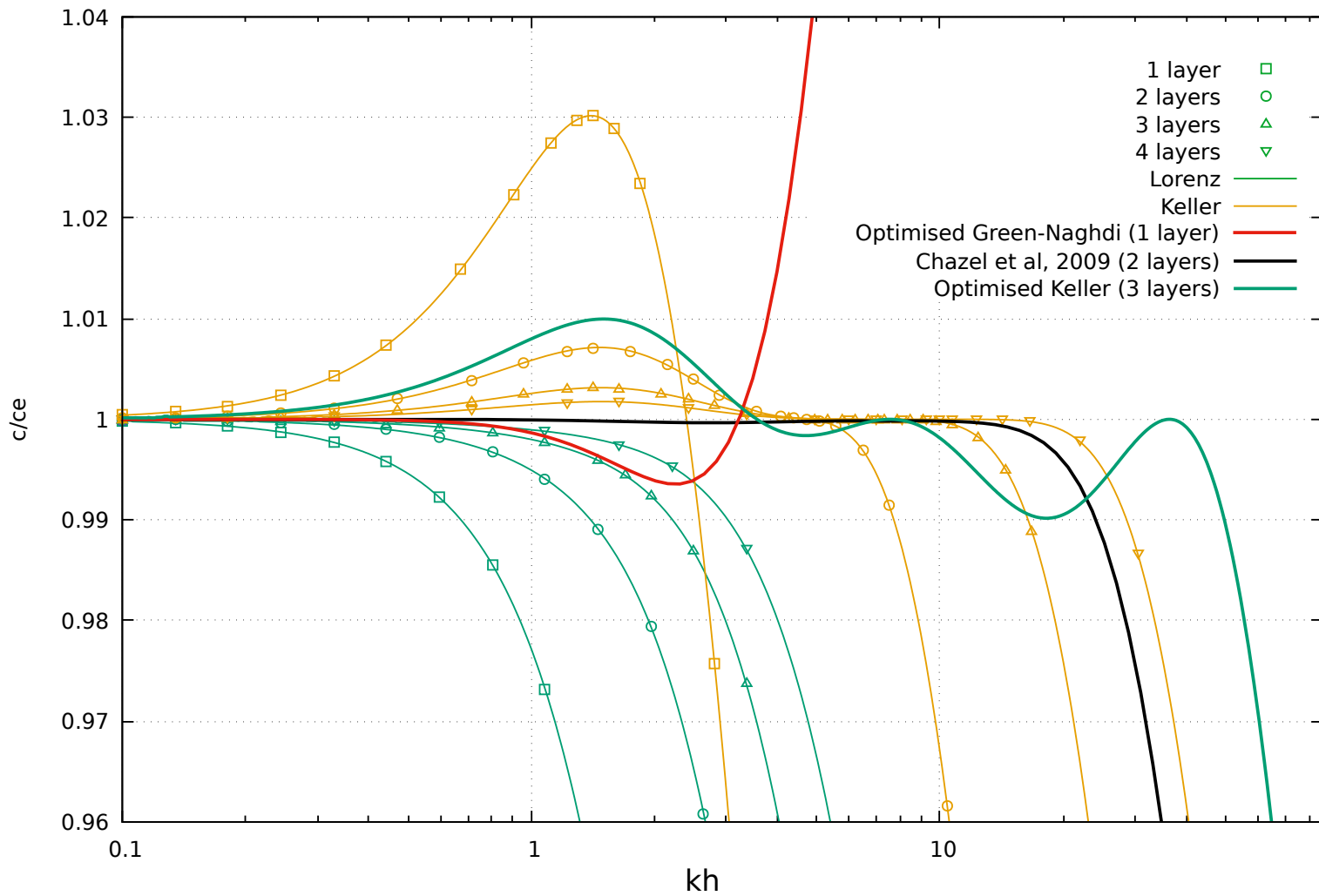
$$c_e^2 = \frac{g}{k} \tanh(kh)$$



$$c_e^2 = \frac{g}{k} \tanh(kh)$$

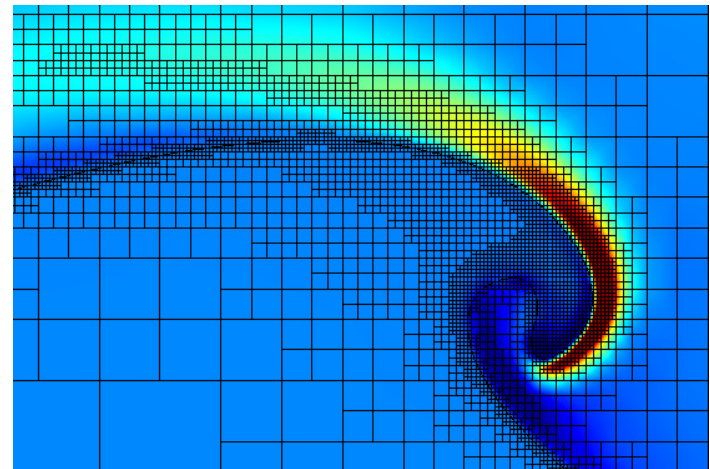
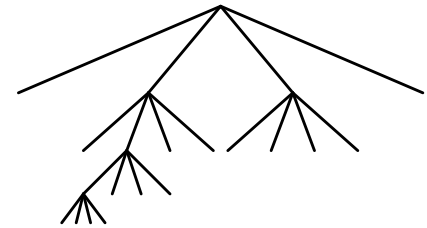
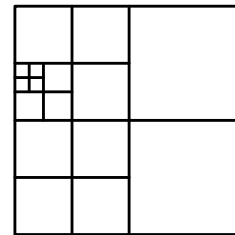


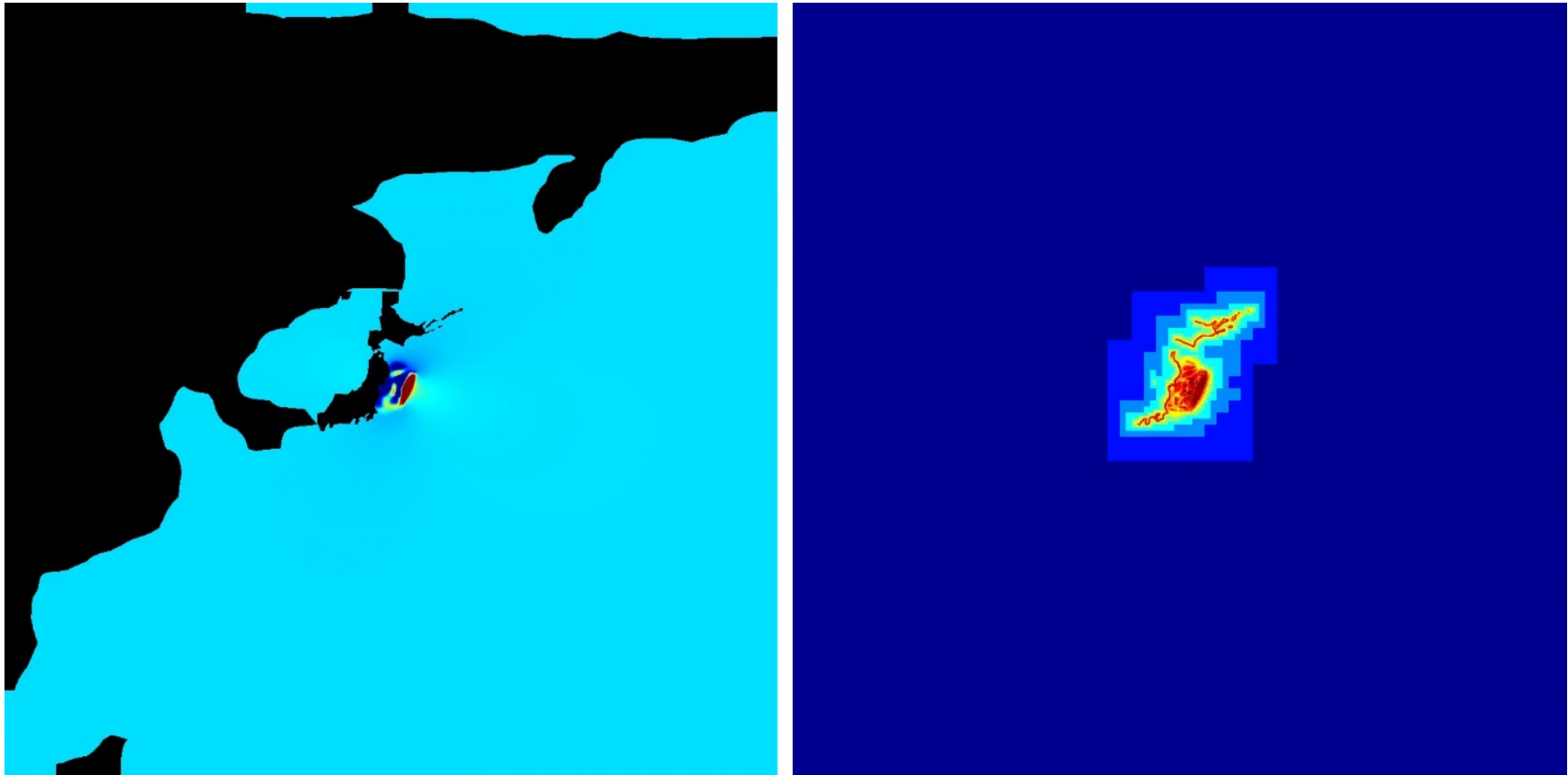
$$c_e^2 = \frac{g}{k} \tanh(kh)$$



$$c_e^2 = \frac{g}{k} \tanh(kh)$$

- Basilisk: open-source, `basilisk.fr`
- Quad/octree adaptive mesh refinement
- Multigrid solver with (vertical) line relaxations for elliptic problems
- MPI/Open MP parallelism
- Load-balancing based on space-filling curves (Z-ordering) (scales to 1000s of cores)
- Decoupled (high-level) numerical scheme / (low-level) memory and loop traversal implementation
- Documented, reproducible and editable examples and test cases: “wikipedia of fluid mechanics”

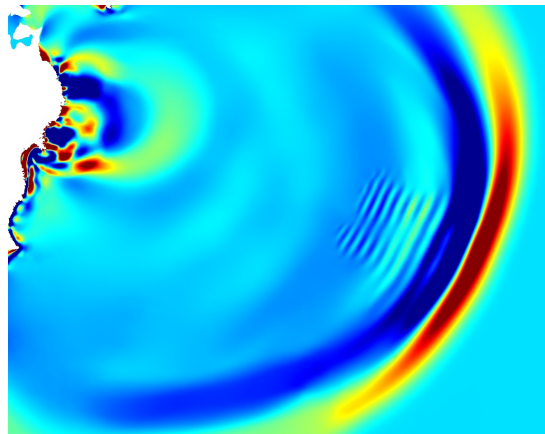




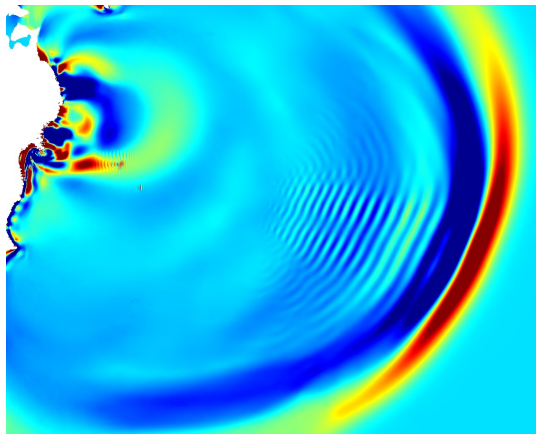
6000×8000 km, spatial resolution: 1–250 km

See also Popinet, 2015 (Green-Naghdi) and Popinet, 2012 (Saint-Venant)

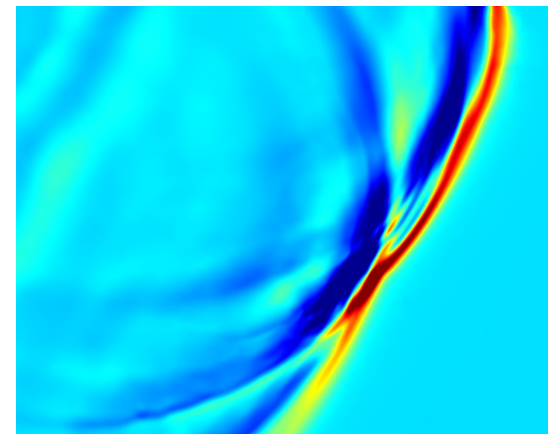
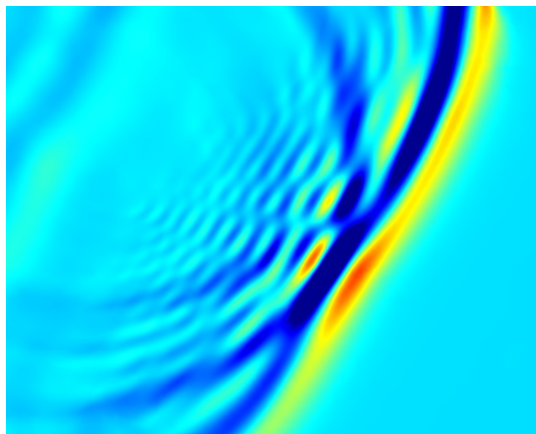
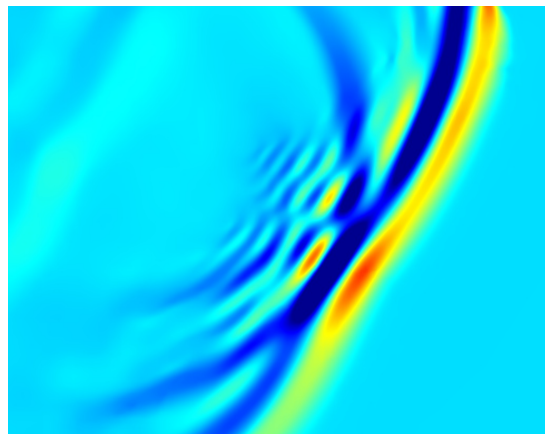
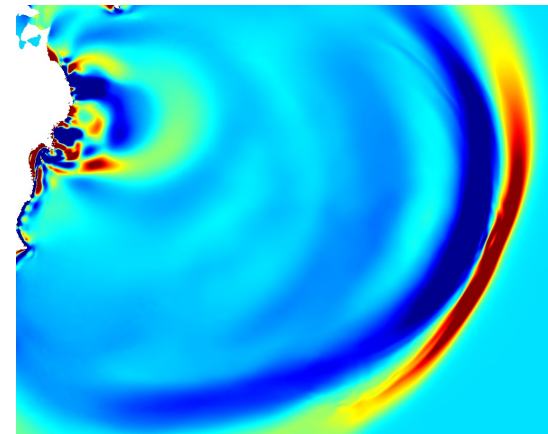
Serre–Green–Naghdi



One-layer non-hydrostatic



One-layer hydrostatic

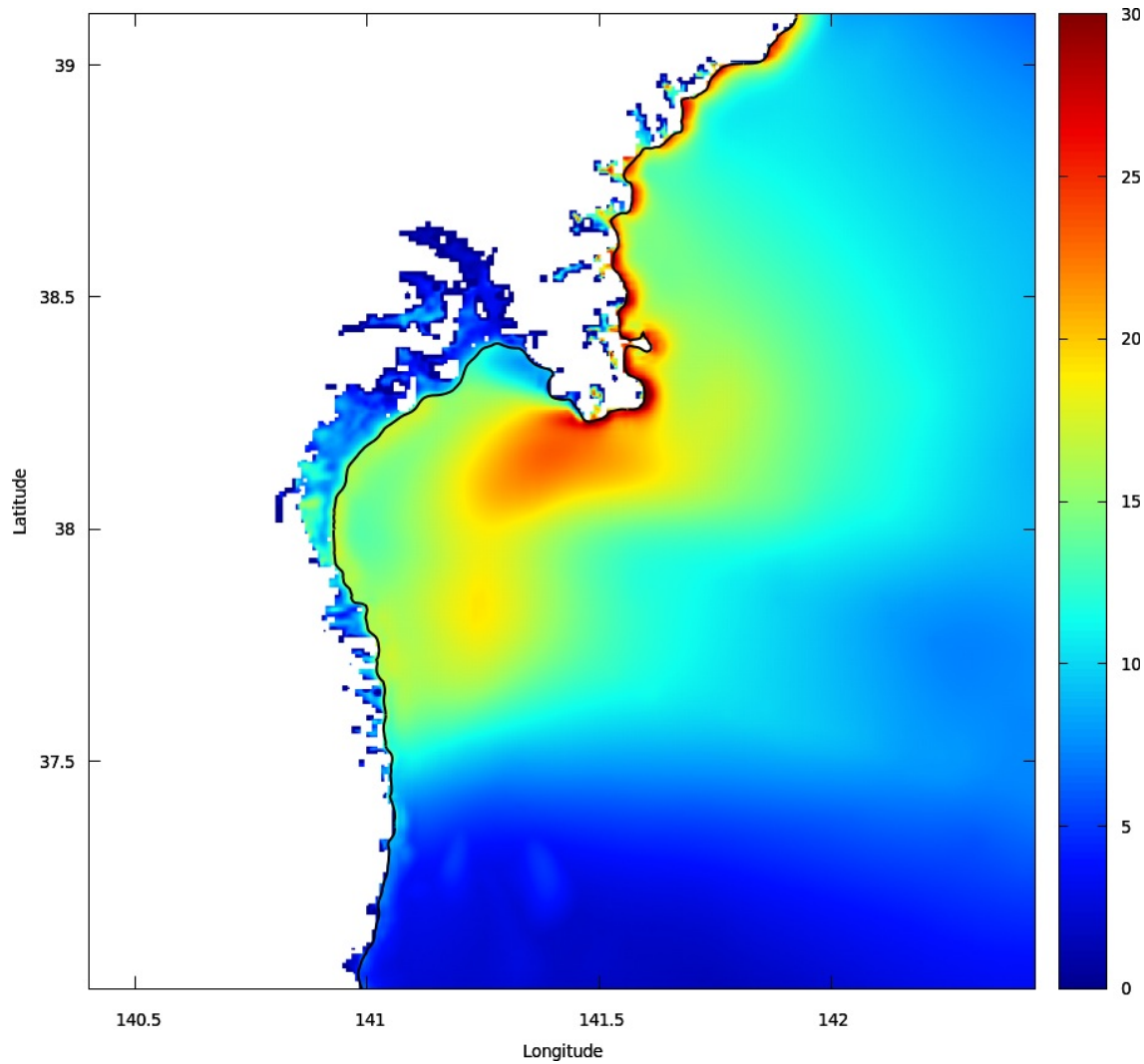


CPU runtime: 7h30

CPU runtime: 4h15

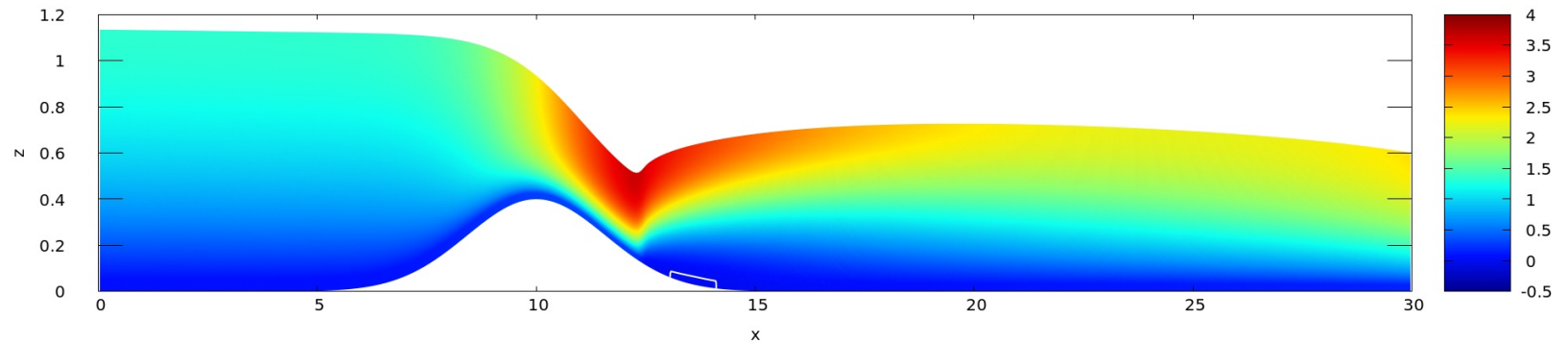
CPU runtime: 5h15

Computational speed $\approx 250\,000$ points $\times$ timesteps / sec

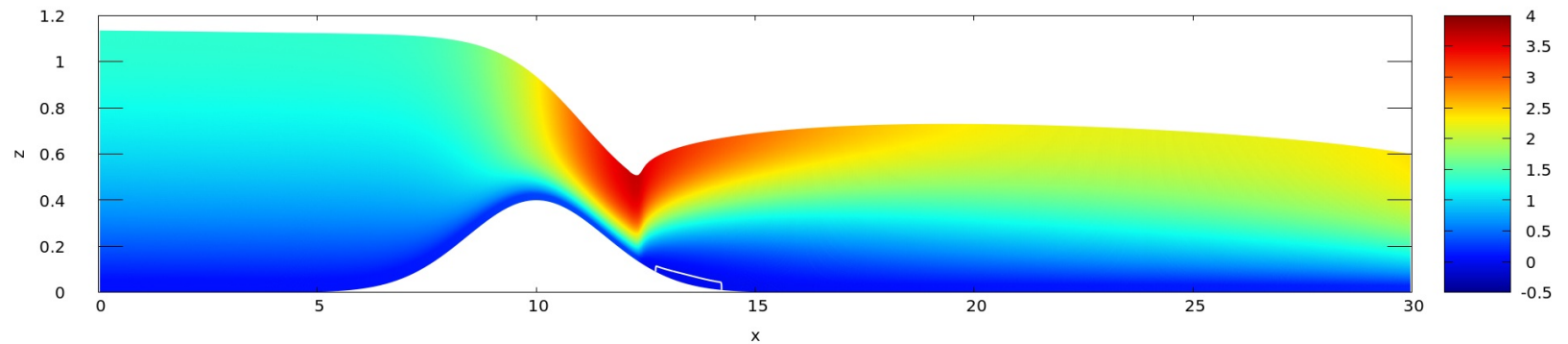


Sendai plain: 140×200 km

Horizontal velocity

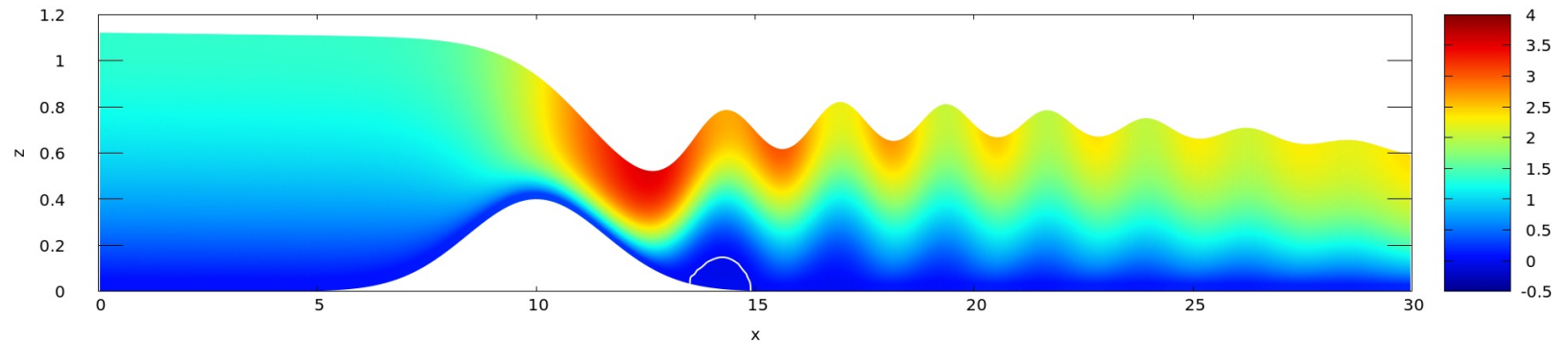


Multilayer hydrostatic

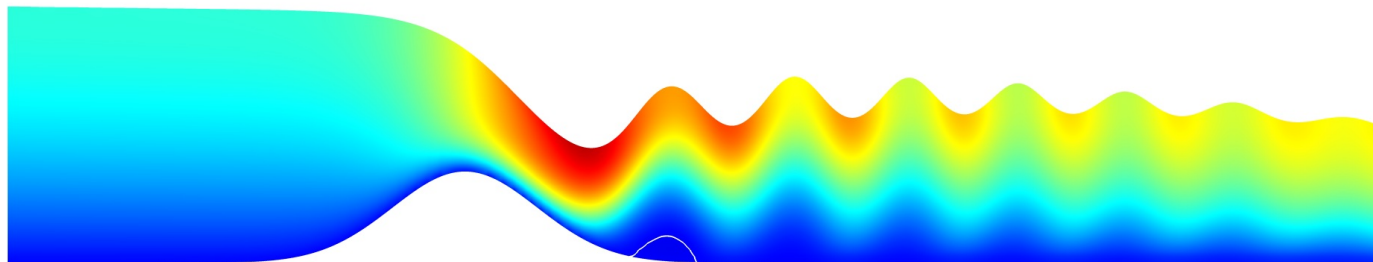


Riemann solver

Horizontal velocity

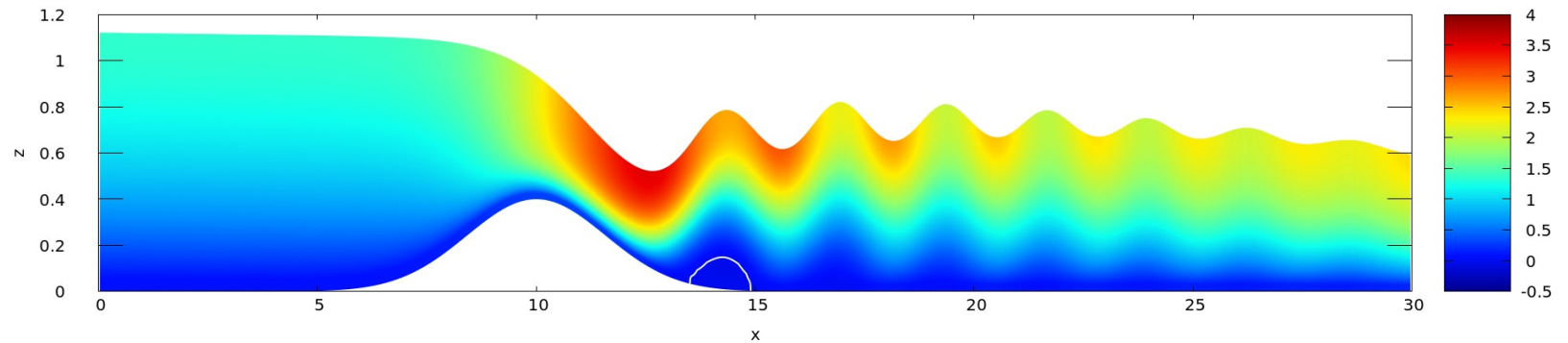


Multilayer non-hydrostatic

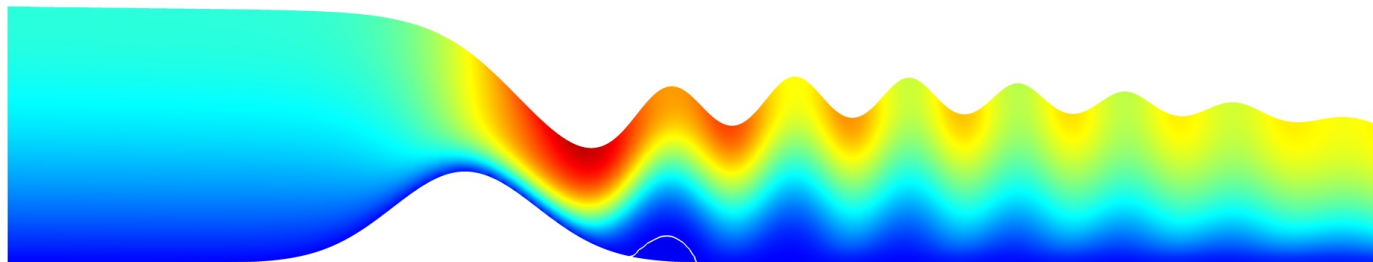


Navier-Stokes VOF

Horizontal velocity

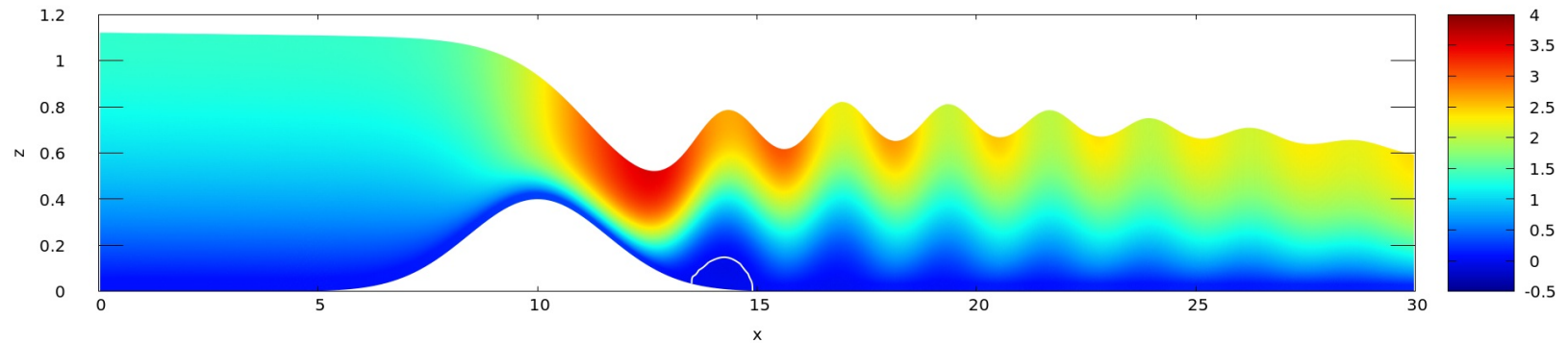


Multilayer non-hydrostatic (runtime: 3 min)

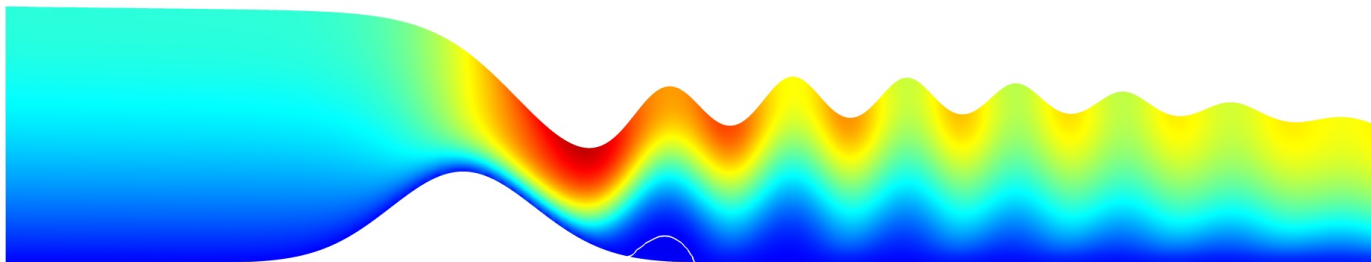


Navier-Stokes VOF

Horizontal velocity

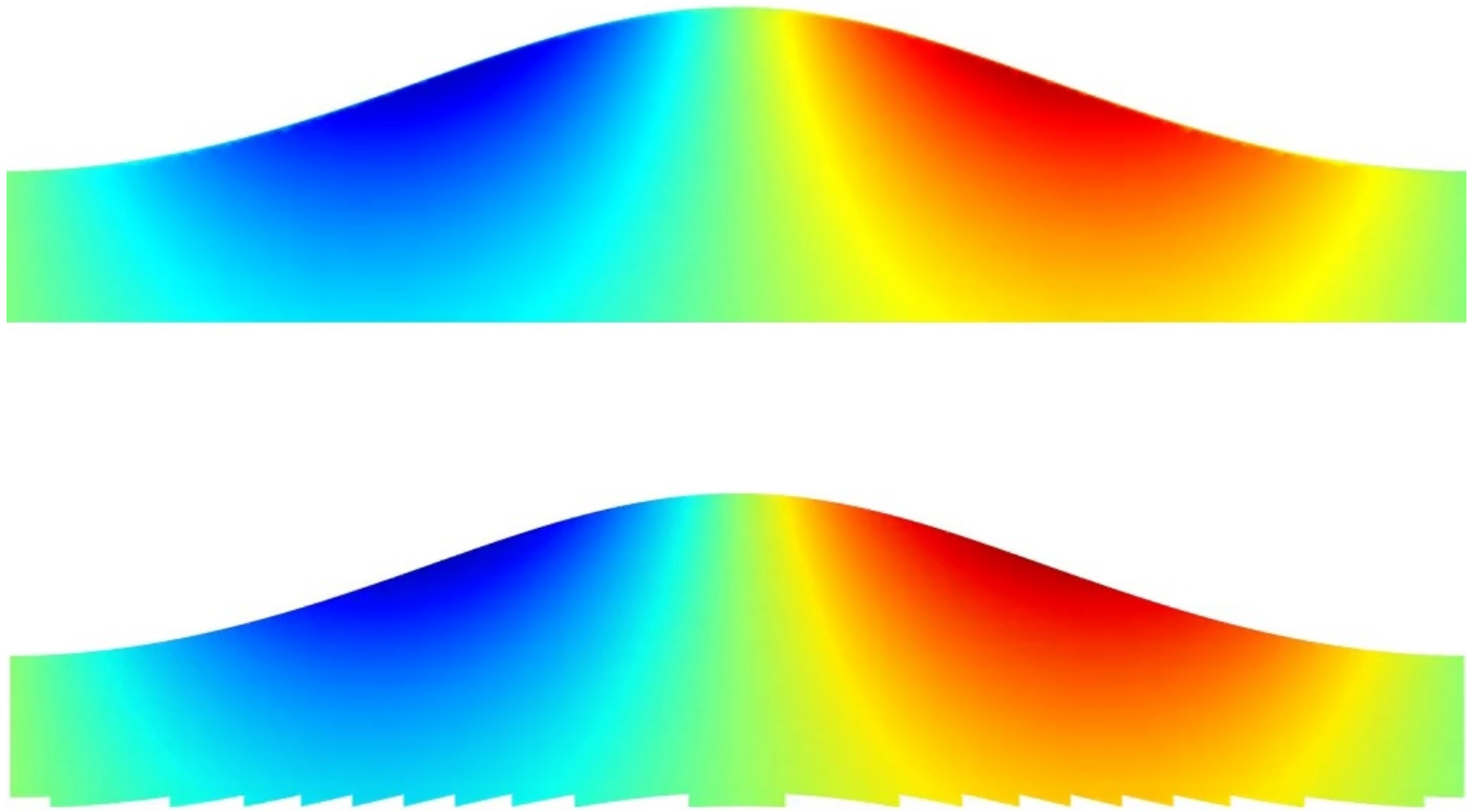


Multilayer non-hydrostatic (runtime: 3 min)

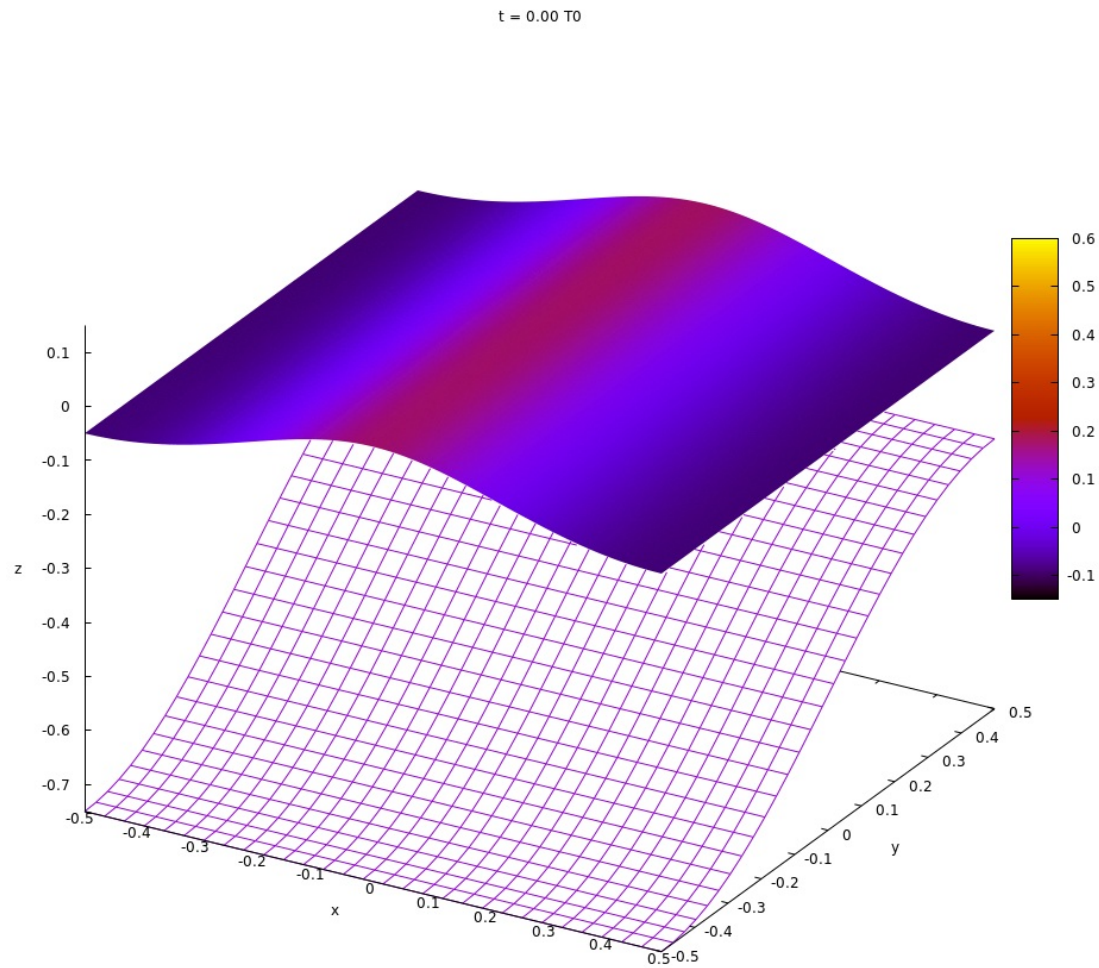


Navier-Stokes VOF (runtime: 1h15)





Vertical velocity: top: Navier–Stokes/VOF, bottom: multilayer



runtime: 13 minutes on 64 cores (MPI), $256^2 \times 80$

- A semi-discrete consistent representation of the incompressible Euler/Navier–Stokes equations with a free-surface.
- This (new) set of equations has a clear physical interpretation and makes a seamless link between the Euler, Saint-Venant and Boussinesq equations.
- The same model gives accurate and efficient solutions for the evolution of metre-scale to kilometer-scale waves.
- Work in progress:
 - Multimaterial flows: densities, rheologies, surface tension etc.
 - Coriolis forces / geostrophic balance
 - Applications to ocean modelling
- Preprint submitted to JCP on HAL and `basilisk.fr`

The choice of a Lagrangian vertical coordinates implies a kinematic condition i.e.

$$w = \partial_t z + \mathbf{u} \cdot \nabla z$$

Note that this condition is physical only at the top and bottom boundaries. Using the vertical difference operator, the fact that $h_k = [z]_k$ and the continuity equation

$$\nabla \cdot (h \mathbf{u})_k + [w - \mathbf{u} \cdot \nabla z]_k = 0$$

we get

$$\begin{aligned} [w]_k &= \partial_t [z]_k + [\mathbf{u} \cdot \nabla z]_k, \\ [w - \mathbf{u} \cdot \nabla z]_k &= \partial_t h_k, \\ -\nabla \cdot (h \mathbf{u})_k &= \partial_t h_k, \end{aligned}$$

which is the layer evolution equation.